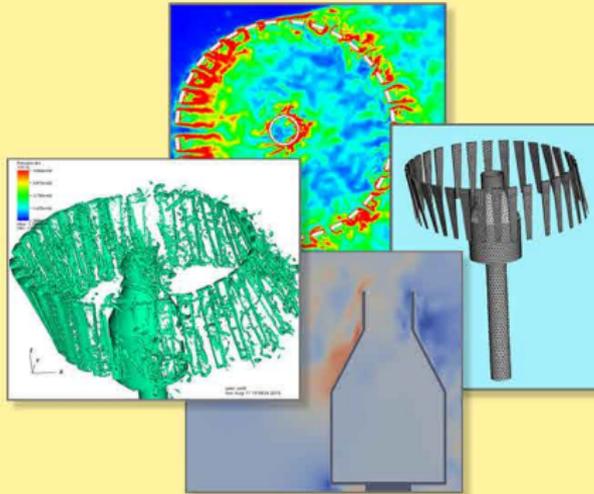


## A CFD evaluation of wind induced errors in solid precipitation measurements



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<sup>(2)</sup> WMO/CIMO Lead Centre “B. Castelli” on Precipitation Intensity, Italy

## A CFD approach to model wind-induced errors

Problem description

### Airflow simulations

Methodology of investigation

RANS Simulations

LES Simulations

### Collection efficiency estimation

Methodology

Particle trajectories

Collection efficiency

### Wrapping up



### Objective

*Quantification of the precipitation measurements errors caused by the wind exposure of catching type gauges by means of fluid-dynamics simulations.*

An under-estimation of the precipitation measurements is generally observed in presence of significant wind regimes.

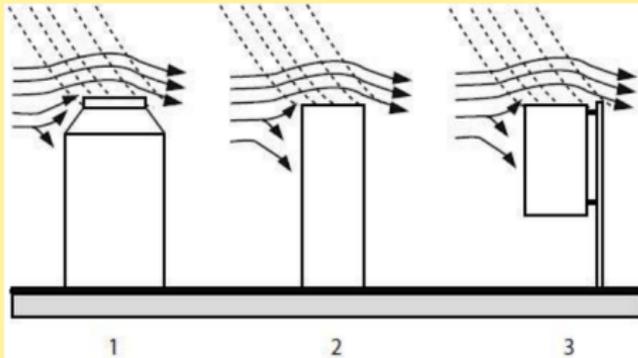


Laboratory experiment by John Kochendorfer, NOAA).

## Objective

Quantification of the precipitation measurements errors caused by the wind *exposure* of catching type gauges by means of fluid-dynamics simulations.

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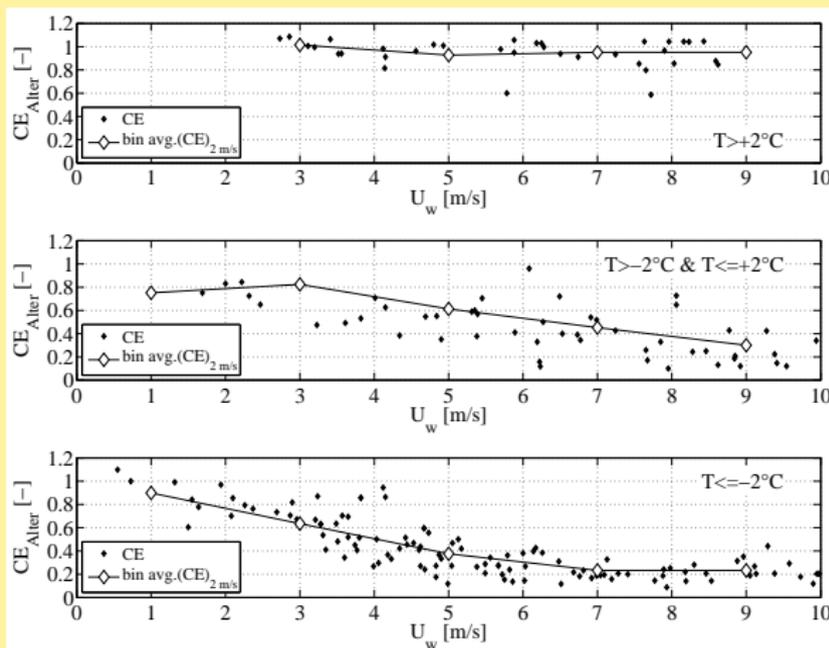
WMO *Guide to Meteorological Instruments and Methods of Observation*.

The **collection efficiency**  $CE$  is commonly represented by the ratio:

$$CE = \frac{h_{meas}}{h_{true}} \quad (1)$$

where  $h_{exp}$  (mm) is the precipitation measured by a gauge exposed to the wind and  $h_{ideal}$  (mm) the value obtained by an ideal instruments not affected by the wind exposure.

Currently available  $CE$  estimations are obtained by means of **comparisons between co-located gauges installed in experimental sites** of time-averaged numerical simulations (Nešpor and Sevruk, 1999; Thériault et. al, 2012)



Courtesy of Dr. Mareile Wolff (Norwegian Meteorological Institute).

# 1. A CFD approach to model wind-induced errors

In many cases the infield  $CE$  estimates are evaluated by accepting as true the measurement obtained with a DFIR shielded gauge.



NCAR/FAA/NOAA field site in Marshall (Colorado, USA).

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The 3D analysis of the air velocity fields has been conducted with two different finite volumes approaches:

- ▶ Time-averaged numerical solutions computed by simulating different wind speed conditions  $U_w$  with a **Reynold Averaged Navier-Stokes equations** (RANS) SST  $k-\omega$  model.
- ▶ Time-dependent analysis using **Large Eddy Simulations** (LES) with Smagorinsky model to solve spatial scales which are smaller than the cell dimension (*sub-grid scales* SGS).

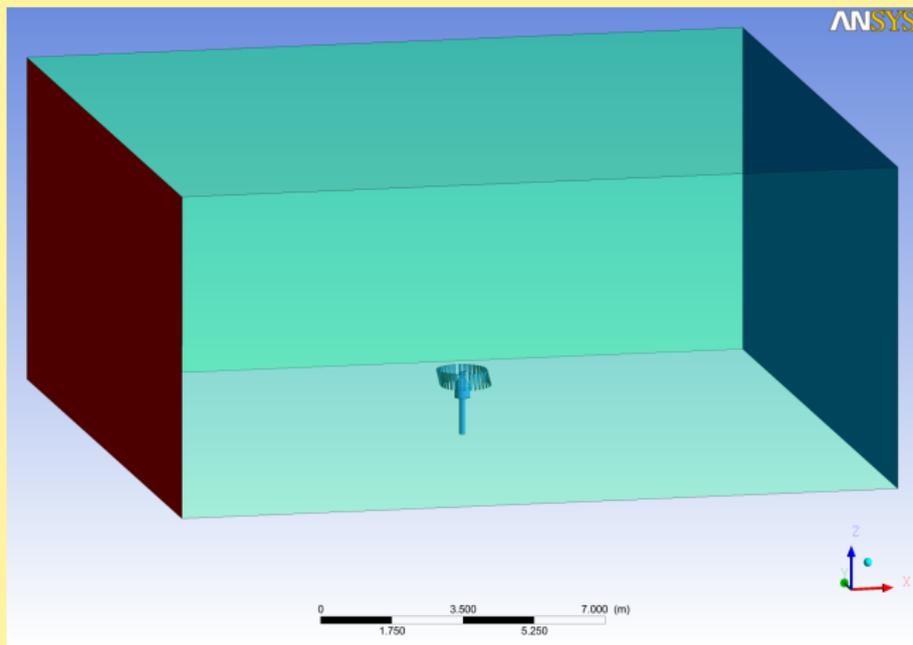


This study focuses on the single Alter shielded Geonor T200B weighing gauge.

## 2. Airflow simulations

### Geometries and boundary conditions

Simulations set-up

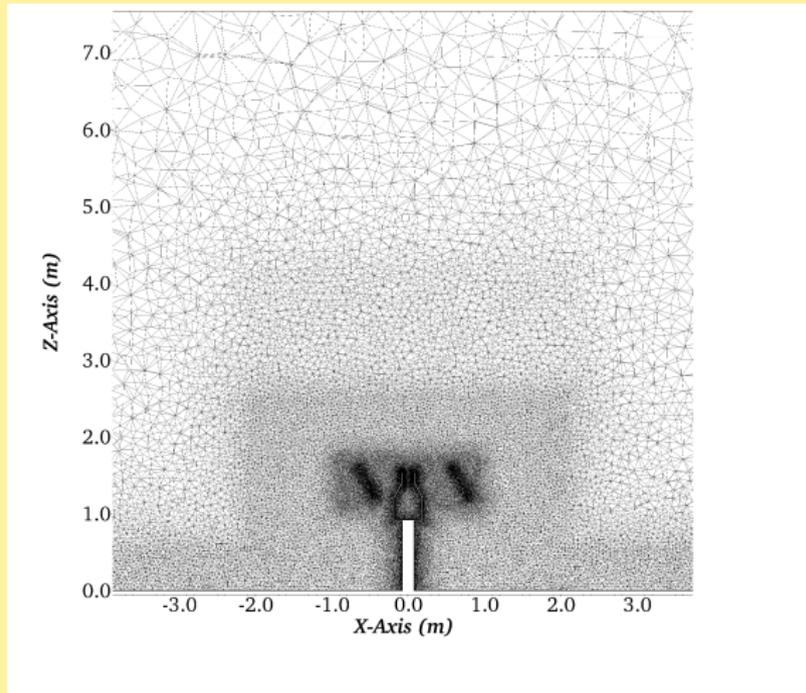


- ▶ The RANS meshes use variable number of elements (ranging from 2 mln to 6 mln) depending on the simulated geometries.
- ▶ The LES meshes are composed by 25/29 mln elements so as to obtain numerical convergence and accurate results.

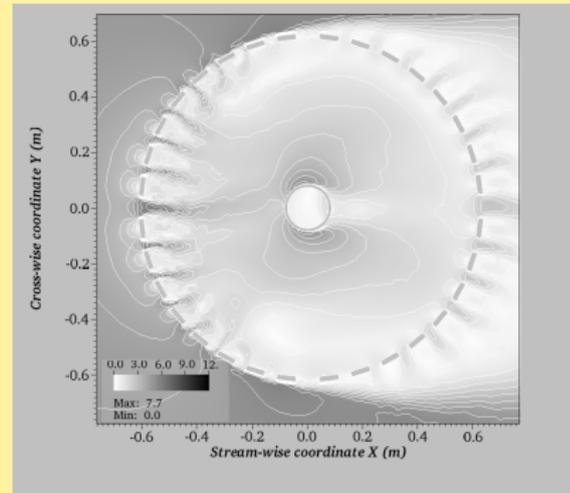
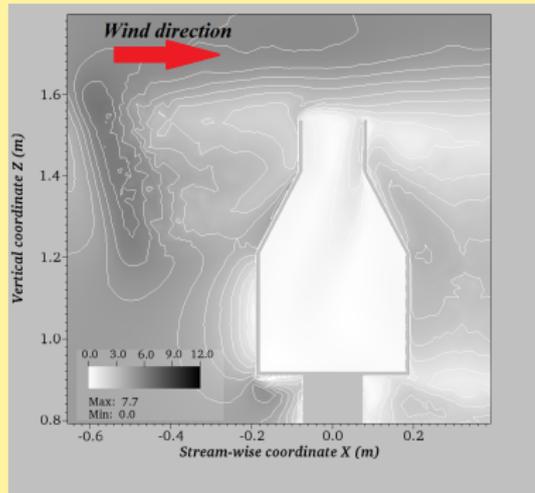
## 2. Airflow simulations

### Discretization of the spatial domain

Simulations set-up



Vertical section ( $y = 0 \text{ m}$ ) of the spatial grid. The plane is parallel to  $U_w$  and passes through the center of the cylindric gauge geometry.

RANS - Wind speed  $U_w = 5 \text{ m/s}$  case

- ▶ Between the upwind windshield fences and the gauge, an attenuation of the time-averaged air velocity with respect to  $U_w$  is shown.
- ▶ The left figure shows an extended zone characterized by high air velocity values above the orifice of the gauge.
- ▶ A comparison with similar literature studies reveals a better level of details of the air velocity field thanks to the finer spatial grid.

**LES** - Wind speed  $U_w = 5 \text{ m/s}$  case

**LES** - Wind speed  $U_w = 5 \text{ m/s}$  case

Vorticity color plots

- ▶ The windshield upwind elements entail a production of turbulence.
- ▶ The airflow transports eddies from the upwind windshield elements to the gauge collecting section with implications for the precipitation trajectories.

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## Wrapping up

- ▶ **Parametrization of the snow particles** (based on Rasmussen et al., 1999):

$$X(d_p) = a_X d_p^{b_X} \quad (2)$$

where  $X$  represents the following quantities: terminal velocity of the particles ( $w_T$ ), volume ( $V_p$ ), density ( $\rho_p$ ) and cross-sectional area ( $A_p$ ). And  $a_x$  and  $b_x$  are empirical coefficients that depends on the crystal types (dry and wet snow).

- ▶ **Particles Size Distribution (PSD):**

$$N(d_p) = N_0 \exp(-\Lambda d_p) \quad (3)$$

with  $N_0 = 5 \cdot 10^6 \text{ m}^{-4}$  and  $\Lambda = 0.5 \text{ mm}^{-1}$ .

- ▶ **Total collection efficiency at given wind speed  $U_w$ :**

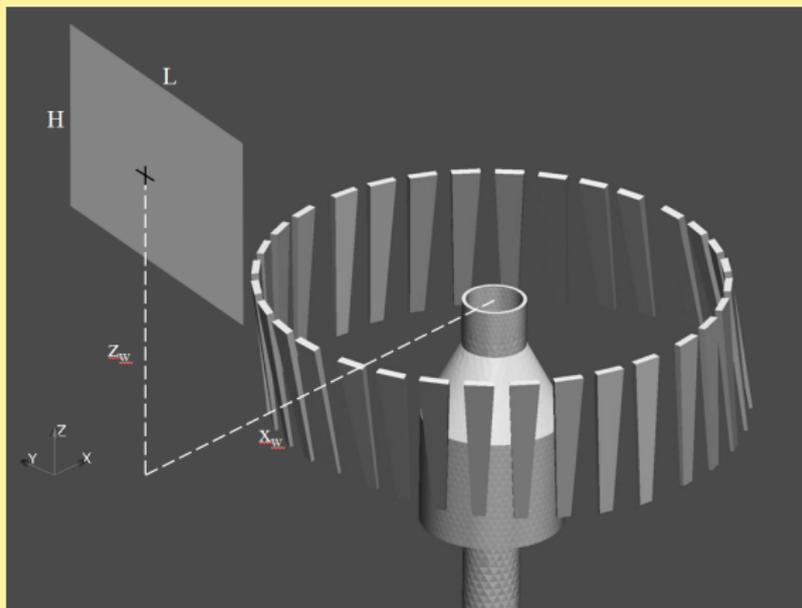
$$CE(U_w) = \frac{\int_0^{d_{pmax}} V_w(d_p) A_{inside}(d_p, U_w) N(d_p) d(d_p)}{\int_0^{d_{pmax}} V_w(d_p) A_{gauge}(d_p, U_w) N(d_p) d(d_p)} \quad (4)$$

where  $V_w(d_p)$  is the water equivalent volume of the precipitation,  $A_{inside}(d_p, U_w)$  the area of the collecting section associated with the entering particles and  $A_{gauge}$  the total area.

### 3. Collection efficiency estimation

#### Initial conditions of the time-dependent analysis

The initial position of the trajectories is defined on a vertical rectangular grid (a *seeding window* with length  $L = 0.4 \text{ m}$  and variable height  $H$ ) located upwind the gauge.



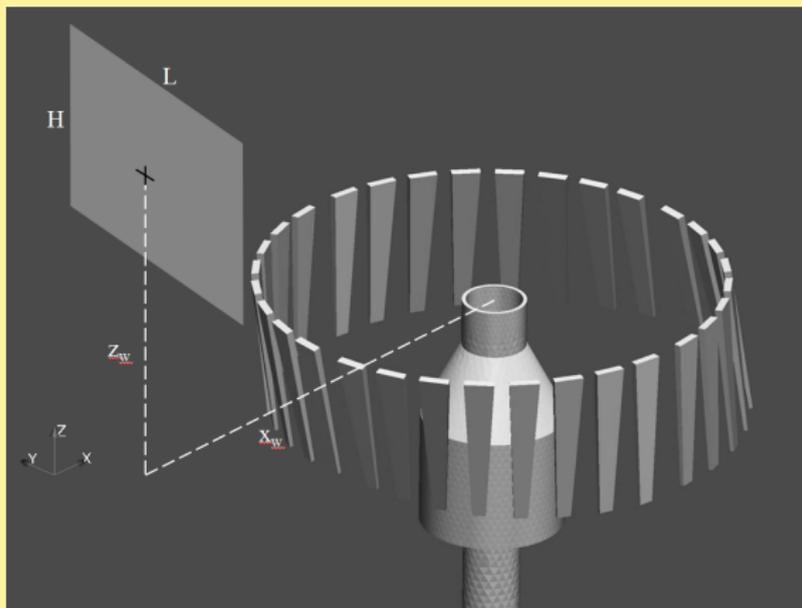
Location of the initial positions of the particles trajectories.

### 3. Collection efficiency estimation

#### Initial conditions of the time-dependent analysis

Particles number:

- ▶ The time-dependent tests **LES** model: 2400 trajectories each run
- ▶ Time-averaged **RANS** model: 3000 to 10000 trajectories

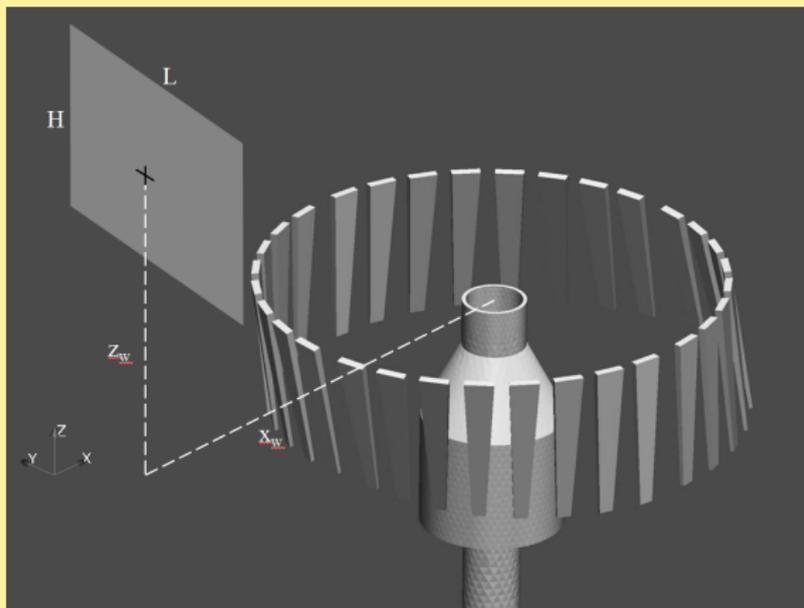


Location of the initial positions of the particles trajectories.

### 3. Collection efficiency estimation

#### Initial conditions of the time-dependent analysis

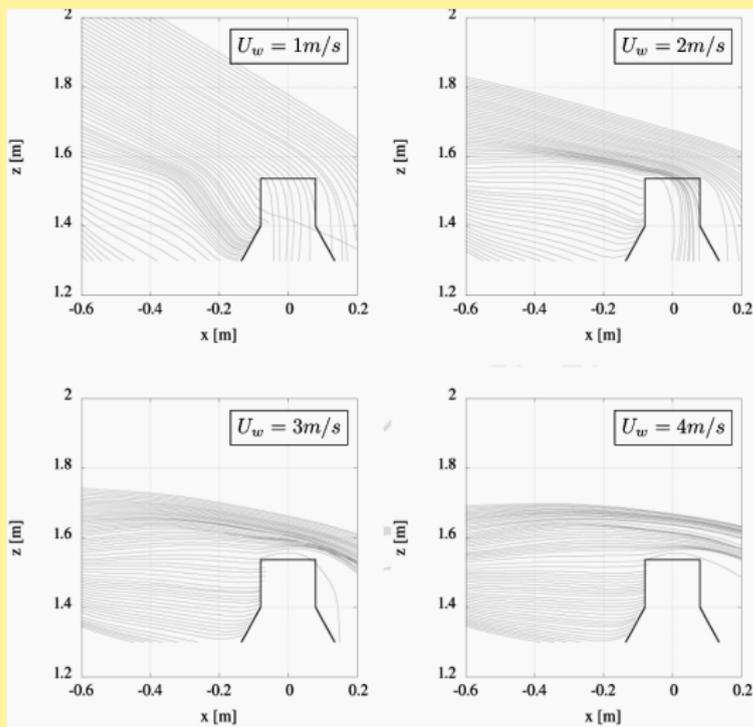
- ▶ 16 different particles diameters covering  $0.25 \text{ mm} < d_p < 20 \text{ mm}$
- ▶ **Two different type of snow here considered: dry and wet**



Location of the initial positions of the particles trajectories.

### 3. Collection efficiency estimation

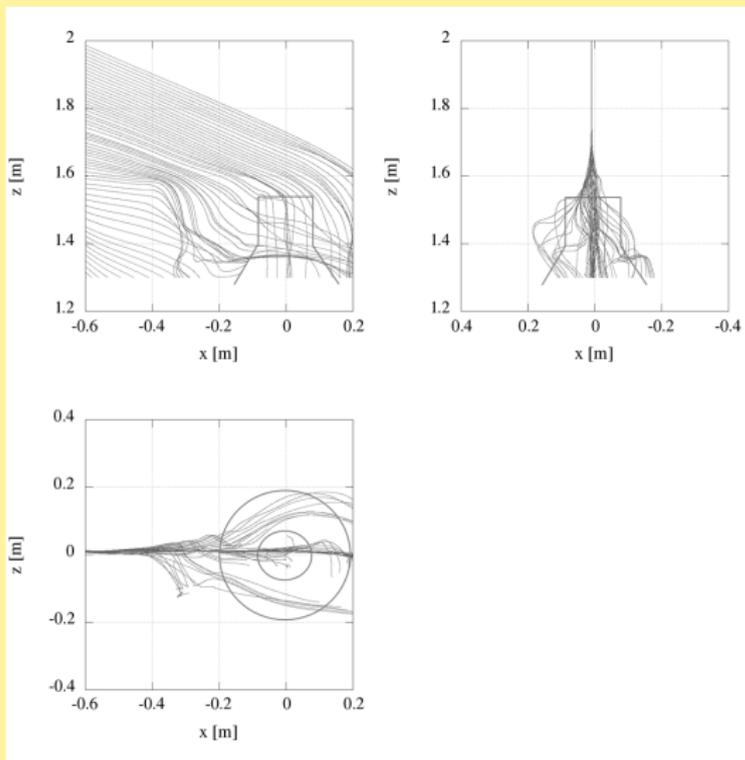
#### Time-invariant model



Time-invariant approach. Dry snow trajectories,  $d_p = 1\text{ mm}$

### 3. Collection efficiency estimation

#### Time-variant model



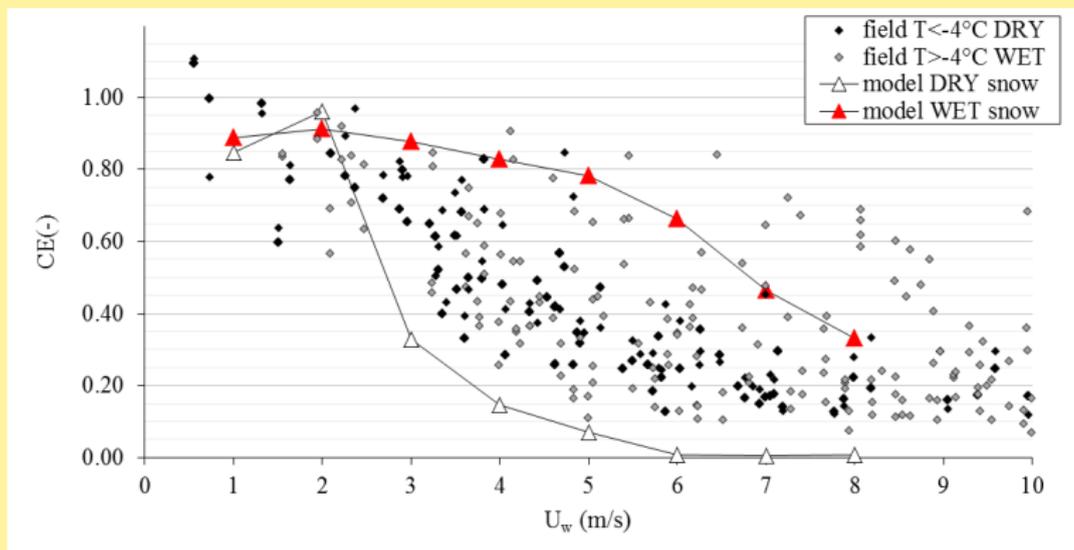
**Time-variant approach.** Orthogonal projection of a choice of **dry snow trajectories**,  $d_p = 0.25 \text{ mm}$  and  $U_w = 1 \text{ m/s}$ .

### 3. Collection efficiency estimation

#### Comparison with infield observations

Collection efficiency

Comparison between collection efficiency  $CE$  obtained with LES simulations (black curves with triangles) and infield observation (grey scale dots).



Courtesy of Dr. Mareile Wolff (Norwegian Meteorological Institute).

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## 4. Wrapping up

- ▶ **The simulation work highlighted a strong sensitivity of the gauge collection efficiency to the micro-physical characteristics of the precipitation particles.** Such sensitivity explains the variability observed in in-field  $CE$  estimates.
- ▶ **It has been also revealed that the single Alter windshield must be considered as a source of turbulence.** Its presence increases the time-dependency of the problem and causes trajectories clustering phenomena.
- ▶ The time-dependent simulations described the time-spatial evolution of the trajectories. **The here adopted CFD simulations are a valuable tool to explain the fundamentals governing collection efficiency.**